Development of airglow temperature photometers with cooled-CCD detectors

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We have developed three airglow temperature photometers with cooled-CCD detectors. The photometers measure rotational temperatures using the airglow emissions of OH and O_2 near the mesopause region (altitude: 80–100 km). The photometers also measure six other airglow and auroral lines at wavelengths of 557.7, 630.0, 777.4, 589.3, 427.8, and 486.1 nm. The CCD detectors are used to distinguish the emission lines in these airglow bands, similarly to those used by the Spectral Airglow Temperature Imagers (SATI). In this paper, we describe the configuration of the photometers, their calibration, the data processing to extract rotational temperatures and emission intensities from the measured airglow spectra, as well as the initial deployment at Platteville, Colorado (40.2°N, 255.3°E), when their observations were compared with the concurrent and nearly collocated observations by a sodium lidar. We obtain a good correlation and some systematic difference of temperatures from the photometers and the lidar, and discuss possible causes of the temperature difference.

Key words: Airglow temperature photometers, airglow emissions, rotational temperature, cooled CCD, mesopause region.

1. Introduction

Mesospheric temperature is an important parameter in the dynamics and chemistry of the middle atmosphere. The temperature can indicate short-term dynamical variations by planetary waves, tides, and gravity waves in the middle atmosphere, as well as long-term cooling of the middle atmosphere associated with the global warming of the troposphere. Sodium lidars and airglow photometers are two major remote-sensing techniques to measure absolute values of the temperatures in the middle atmosphere. The former gives accurate absolute temperatures with their height profiles in the sodium layer at ~80–105 km (e.g., She *et al.*, 2000). The latter gives temperatures averaged over the airglow emission layers. The airglow photometer is a compact, low-cost instrument and can be easily automated.

The airglow photometers have used the hydroxyl (OH(v', v'')) and molecular oxygen (O₂b(0,1)) airglow band emissions to measure the temperatures through rotational lines (e.g., Chamberlain, 1961; Meriwether, 1975; French *et al.*, 2000; Takahashi *et al.*, 2002; Gavrilyeva and Ammosov, 2002; Slanger *et al.*, 2003; Sigernes *et al.*, 2003; Cho *et al.*, 2004; Taori *et al.*, 2005). Figure 1 shows the relative line intensities of the OH(6,2) Meinel Q- and P-branches and the O₂(0,1) Atmospheric band system ($b^1\Sigma_g^+ \rightarrow X^3\Sigma_g^-$)

at a temperature of 200 K (Langhoff *et al.* (1986) for OH; Krupenie (1972) for O₂). The relative line intensities vary depending on the temperature of the emitting molecules. It is believed that the OH rotational level populations are in a thermodynamic equilibrium with the ambient gas at least for the lower rotational levels (Pendleton *et al.*, 1993). The lifetime of the O₂b (v = 0) state (> 10 s) seems to be sufficient to reach a thermodynamic equilibrium with the ambient atmosphere. By measuring the intensities at several rotational lines, one can measure the temperature of the atmosphere. The OH and O₂ bands have emission layers near the mesopause region with peaks at ~86 km and ~94 km, respectively, and thicknesses of ~8–10 km (e.g., Zhang *et al.*, 1993; Zhang and Shepherd, 1999).

A highly sensitive cooled-CCD camera was originally used as a detector of the airglow photometer named "Mesospheric Oxygen Rotational Temperature Imager (MORTI)" for the measurement of the O₂ band (Wiens *et al.*, 1991). The Spectral Airglow Temperature Imager (SATI) was subsequently developed as a revision of MORTI, measuring rotational temperatures of both the OH and O₂ bands (Wiens *et al.*, 1997; Sargoytchev *et al.*, 2004). SATI has been widely introduced in Spain, Japan, and Canada (e.g., Won *et al.*, 2003; López-González *et al.*, 2004; Shiokawa *et al.*, 2004; Cho and Shepherd, 2006).

As described by Sargoytchev *et al.* (2004), SATI uses a cooled-CCD detector to image airglow lines as concentric circles with spectral scanning in the radial direction and sky

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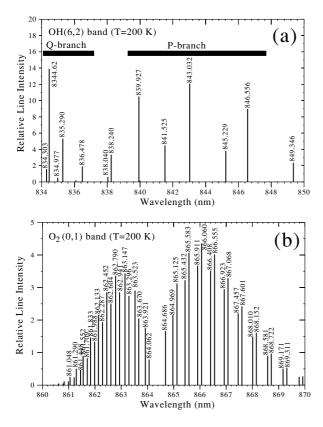


Fig. 1. Relative line intensities of (a) OH(6,2) band Q- and P-branches and (b) O₂(0,1) band at a temperature of 200 K based on the theoretical transition probabilities by Langhoff *et al.* (1986) (OH) and Krupenie (1972) (O₂).

azimuth in the azimuthal direction. It has an annular field of view in the sky, with a radius in zenith angles of 26.32° – 33.55° . The temperature and intensity of airglow emission are obtained for 12 azimuthal directions. The narrow-band filters of SATI work as a Fabry-Perot etalon to make the spectral scanning in the radial direction on the CCD. The rotational temperatures can be determined with a standard deviation of 1.7 K for an exposure time of 2 min.

In this paper, we report the details of three airglow temperature photometers with cooled-CCD detectors. The photometers have a basically similar optical configuration to that of SATI. However, three revisions have been made. One is that the new photometer measures OH(6,2) Pbranches instead of Q-branches of SATI. The OH(6,2) Pbranches have been widely used in previous photometers and their transition probabilities have been well investigated (e.g., Greet et al., 1998; French et al., 2000 and references therein). SATI used Q-branches mainly because it is easier to fit the Q-branch spectra into a limited CCD size, since the spectral width of the Q-branch is narrower than the Pbranch, as shown in Fig. 1. However, the rotational temperature measurement through OH(6,2) Q-branches contains possible systematic errors, irrespective of the specific choice of the Einstein coefficients, as pointed out by Pendleton and Taylor (2002).

The second revision is that the new photometer has a small aperture (28.7 mm ϕ) at the top of the optics without a conical mirror. The conical mirror introduced by MORTI and SATI makes it possible to measure the horizontal prop-

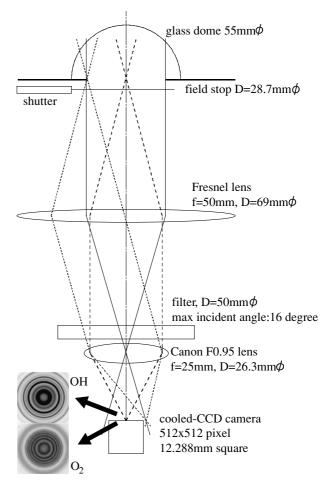


Fig. 2. Schematic illustration of the optics of the airglow temperature photometer.

agation of gravity waves by setting the field of view as a circular shape in the sky with zenith angles of 26.32° – 33.55° . However, because of this conical mirror and associated complicated structure at the top of the optics, it was difficult to make a spectral calibration through the entire optics of SATI. The simple optics with a small aperture of the new photometer allows us to fully calibrate the spectral response of the optics.

The third revision is that the three new photometers have two identical filters (six filters in total) for both OH and O_2 bands to facilitate cross calibrations between the filters and to monitor for possible degradation of a specific filter during long-term measurements.

2. Optical Configuration

Figure 2 shows the optical system of the airglow temperature photometer. We use a thinned and back-illuminated cooled CCD with 512 × 512 pixels made by the Hamamatsu Photonics (model: C4880-30-24A). The CCD has a quantum efficiency of more than 90% in the visible wavelengths and more than 60% at 850 nm. The size of one pixel is 24 μ m, giving a CCD size of 12.288 × 12.288 mm. In order to reduce the relative read-out noise, we use 4 × 4 onchip binning of the CCD. Thus, the CCD output image is 64 × 64 large pixels. The CCD surface is cooled down to less than -60°C using a thermoelectric cooler. The dark noise is

Channel	Center	Band	Peak	Refractive	Exposure	Species
	wavelength	width	transmission	index	time	
	(nm)	(nm)	(%)		(s)	
1	847.2	0.7	> 45	1.45	60	OH(6,2) P ₁ (2,3,4)
2	847.2	0.7	> 45	1.45	60	OH(6,2) P ₁ (2,3,4)
3	867.7	0.25	> 35	2.05	60	$O_2b(0,1)$
4	867.7	0.25	> 35	2.05	60	$O_2b(0,1)$
5	558.5	1.0	> 50	2.05	10	OI(557.7 nm)
6	630.9	1.0	> 55	2.05	10	OI(630.0 nm)
7	778.5	0.5	> 60	2.05	20	OI(777.4 nm)
8	590.1	0.5	> 50	2.05	10	Na(589.3 nm)
9	428.4	1.0	> 25	1.45	60	N ₂ ⁺ (1NG, 427.8 nm)
10	486.8	1.0	> 45	2.05	60	$H\beta$ (486.1 nm)
11*	878.3	0.3	> 50	2.05	60	OH(7,3) R ₁ (1,2,3)

Table 1. Filter specifications of the airglow temperature photometers.

*Photometer 1 only.

less than 1 electrons/pixel/s, while the read-out noise (root-mean-square) is ~ 10 electrons.

The basic interference optics consist of the 50-mm ϕ filter and the Canon F0.95 lens. The light rays that pass through the narrowband interference filter with incident angles of 0° and 19.1° (= tan⁻¹(12.288 mm × $\sqrt{2}$ / 2 /25 mm)) are focused on the center and the four corners of the CCD, respectively. The center wavelength of the narrowband interference filter shifts toward a shorter wavelength with an increasing angle of the incident light. The wavelength shift is given as,

$$\lambda = \lambda_0 \left(1 - \frac{\mu_0^2}{\mu^2} \sin^2 \theta \right)^{1/2}, \qquad (1)$$

where λ , λ_0 , θ , μ_0 , and μ are the shifted wavelength, original wavelength, incident angle, and refractive indices of the external medium ($\mu_0 = 1.0$ for air) and the filter, respectively. Typical values of μ are 1.45 or 2.05 for interference filters. In the case of $\lambda_0 = 840$ nm, the incident angle of 10° gives wavelength shifts of 3 and 6 nm for $\mu = 2.05$ and 1.45, respectively. For OH and O₂ airglow bands, several emission lines exist in the range of this wavelength shift, as shown in Fig. 1. For the OH measurement, we took the lower refractive index of 1.45 for the filter, so the wide wavelength range of OH(6,2) P(2), P(3), and P(4) lines can be put into a CCD image. As a result, the output image on the CCD shows concentric fringes, each of which corresponds to an emission line, as shown in Fig. 2. By taking the intensity ratio of these fringes, one can measure the rotational temperature of the emitting molecules. By this method, the CCD gives the advantage of two-dimensional imaging in the wavelength range. The MORTI and SATI put a conical mirror at the location of the top field stop to obtain azimuthal information of the sky.

The Fresnel lens (focal length: 50 mm, diameter: 69 mm) is introduced to smear out the structures in the sky, such as stars and airglow structures by gravity waves. If the Fresnel lens is removed, these sky structures would be projected on the CCD together with the interference fringes, thereby preventing accurate measurement of the line intensities. Using the Fresnel lens, the sky is completely defocused and the image at the 28.7-mm ϕ field stop at the top of the optics is projected onto the CCD. The incident light passes

through the filter with a maximum angle of 16° . This angle is determined by the field stop at the top of the optics ($16^{\circ} = \tan^{-1}(28.7 \text{ mm/2/50 mm})$) and corresponds to the field of view of the photometer. Thus, the photometer measures rotational temperatures and airglow emission rates averaged over a zenith area with zenith angles less than 16° . These configurations are basically identical for the three photometers, although the shutter of Photometer 1 is given by a wheel above the Fresnel lens.

The 50-mm ϕ interference filter is on a wheel, which can mount a maximum 12 filters in it. Table 1 lists the specifications of the narrowband interference filters used for the three photometers. The three photometers have ten filters with identical specifications. For the rotational temperature measurements of OH and O2, two filters with identical specifications are used in each photometer in order to make a cross calibration and to monitor possible degradation of the filters during a long-term measurement. Photometer 1 has an extra filter to measure the OH(7,3) *R*-branches for an experimental purpose. The filters for 557.7, 630.0, 777.4, and 589.3 nm are for the measurement of mid- and low-latitude airglow emissions. The filters of 427.8 nm $(N_2^+(1NG, 0-1))$ and 486.1 nm (H β) are for atmospheric emissions associated with energetic particle precipitation from the terrestrial ring current (e.g., Tinsley et al., 1984). The narrowband filters of channels 3, 4, and 11 are made with two cavities, while other filters are made with three cavities.

The exposure time of each channel is also listed in Table 1. The filter sequence can be set by a program. Usually we take exposures of channels 1–8 sequentially for five times and then take exposures of channels 9–11 and dark images. Such a sequence gives time resolutions of 5.5 min for channels 1–8 and 32.5 min for channels 9–11.

3. Calibration

The output count N_i at the *i*th pixel of the photometer is given as

$$N_i = a_i t \int I(\lambda) T_i(\lambda) d\lambda + N_d, \qquad (2)$$

where a_i , t, λ , $I(\lambda)$, $T_i(\lambda)$, and N_d are absolute sensitivity, integration time, wavelength, intensity of the incident light (in Rayleigh/nm), spectral transmission, and dark count, respectively. In order to calculate rotational temperature and

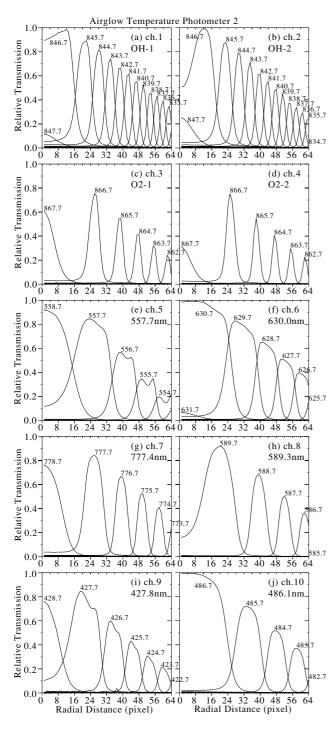


Fig. 3. Relative transmissions for 10 filters of Photometer 2 measured by using a monochromatic light source from an 8-inch integrating sphere. The transmission images are averaged over the azimuthal direction. The abscissa is the radial distance from the center of the interference fringes. The numbers near the peak of the curves indicate wavelengths of incident light in unit of nm.

intensity of airglow from the fringe image of the photometer, we need to obtain the two parameters, spectral transmission $T_i(\lambda)$ and absolute sensitivity a_i , through the calibration. Assuming an azimuthal symmetry, we integrate the fringe images in the azimuthal direction. Thus, the pixel number *i* indicates radial distance from the center of the fringe. The dark count N_d can be obtained by taking an image with the shutter closed.

To obtain the spectral transmission function $T_i(\lambda)$, we used a monochromatic light with a wavelength width of 0.1 nm generated by a grating spectrometer of the National Institute of Polar Research (NIPR). Because the CCD is focused to the 28.7-mm ϕ hole on the field stop at the top of the photometer (Fig. 2), we need to illuminate the hole uniformly by the monochromatic light. For that purpose we introduced an integrating sphere with a diameter of 8 inches. The monochromatic light from the grating spectrometer is put into the integrating sphere. The sphere has a 2-inch (50.8 mm ϕ) window at the 90° location from the light input. The window is set to the 28.7-mm ϕ hole of the photometer to put the monochromatic light into the photometer uniformly. This process can be done because of the small aperture of the photometer. For SATI and MORTI, this calibration was difficult because of their large apertures and the conical mirror on the top of the optics.

For the spectral calibration, the output count $N_{i,k}$ for the monochromatic light input with a wavelength of λ_k is expressed as,

$$N_{i,k} = a_i t I(\lambda_k) T_i(\lambda_k) \Delta \lambda_k + N_d, \qquad (3)$$

where $\Delta \lambda_k = 0.1$ nm for the present case. From Eq. (3), the spectral transmission function $T_i(\lambda_k)$ is obtained as,

$$T_i(\lambda_k) = \frac{N_{i,k} - N_d}{a_i t I(\lambda_k) \Delta \lambda_k}.$$
(4)

Because we do not know a_i and the absolute intensity $I(\lambda_k)$ of the monochromatic light, the transmission function can be obtained as relative values normalized by a maximum transmission at i_0 and k_0 . We consider the dependence of the spectrometer irradiance $I(\lambda_k)$ on wavelength λ_k , which is basically the variation of the irradiance of the tungsten lamp.

Figure 3 indicates the spectral transmission $T_i(\lambda_k)$ obtained by the above calibration for the ten filters of Photometer 2 as a function of λ_k and radial distance *i* from the center of the fringes. These curves are normalized by the maximum transmission of all the radial distances *i* and λ_k . The $T_i(\lambda_k)$ curves are indicated every 1 nm in this figure, while the calibration is done for every 0.1 nm. As the wavelength decreases, the transmission peak shifts outward as expected from Eq. (1). The width of the transmission becomes narrower for shorter wavelengths (larger incident angles).

The curves in channels 5 and 9 are slightly distorted at shorter wavelengths. This distortion can happen with threecavity filters, which have a square-shape transmission for 0° incident angle. These distortions do not affect the measurements, since we fit these transmission functions directly to the observed airglow spectra to obtain the airglow emission rate.

To obtain the absolute sensitivity a_i in Eq. (2), we used a panchromatic (white) light source with a known intensity, provided by an integrating sphere with a diameter of 2 m at NIPR. The 28.7-mm ϕ hole on the field stop at the top of the photometer is illuminated uniformly by this panchromatic light source. For the absolute-sensitivity calibration, the output count N_i from a known light source $I(\lambda)$ (R/nm) is

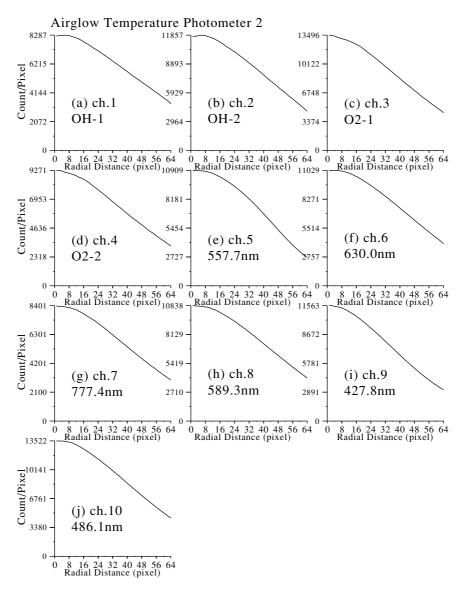


Fig. 4. Azimuthally-averaged distribution of output count per CCD pixel obtained by putting the panchromatic uniform light from the 2-m integrating sphere to Photometer 2. The images are averaged over the azimuthal direction, similarly to that of Fig. 3.

given by writing Eq. (2) in summation form as,

$$N_i = a_i t \sum_k I(\lambda_k) T_i(\lambda_k) \Delta \lambda_k + N_d.$$
⁽⁵⁾

Thus, the absolute sensitivity a_i can be obtained as

$$a_i = \frac{N_i - N_d}{t \sum_k I(\lambda_k) T_i(\lambda_k) \Delta \lambda_k}.$$
(6)

The transmission function $T_i(\lambda_k)$ (Eq. (4)) normalized by the maximum transmission can be used in Eq. (6) to calculate a_i .

Figure 4 shows the azimuthally-averaged distribution of output counts per pixel obtained by putting the panchromatic uniform light from the 2-m integrating sphere into Photometer 2. The dark counts N_d have been subtracted from these data. There is a significant limb-darkening from the center to the edge of the images for all channels. The uniform light at the top of the optics becomes significantly non-uniform with counts less than 40% at the edge of the

image compared to that at the center. This limb-darkening is mainly caused by the Canon F0.95 lens, and it may cause a systematic error of the output rotational temperatures if the optics are not properly calibrated.

Figure 5 indicates the absolute sensitivities a_i (count/R/s) for ten channels of Photometer 2, calculated by Eq. (6) using the data in Figs. 3 and 4. The sensitivity ranges from 0.5 to 2.5 count/R/s, giving an estimate that a 60-s exposure of 100 R airglow would produce 3,000–15,000 counts. The sensitivity is lower in channels 3 and 4 because the narrower bandwidth of the filter (0.25 nm) results in lower transmission.

4. Synthetic Spectra

In the actual observation of the sky, the airglow emission rate is proportional to the peak counts of the fringes. However, if several emission lines with a small wavelength difference, like those in Fig. 1, are included in one fringe image, they contaminate each other, because the spectral transmission functions have certain widths, as shown in Fig. 3.

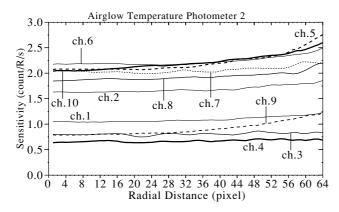


Fig. 5. Sensitivity in unit of count/Rayleigh/s for each channel and each radial distance from the center of the images.

In order to take this spectral contamination into account, we need to fit synthetic spectra to the observed fringes. The synthetic spectra are defined as follows.

If there are several emission lines with intensities of I_1 , I_2 , ..., I_n (Rayleigh) at wavelengths of λ_1 , λ_2 , ..., λ_n , the output count N_i (count/pixel) at the *i*th radial distance of the photometer is given from Eq. (2) as

$$N_{i} = a_{i}t(I_{1}T_{i}(\lambda_{1}) + I_{2}T_{i}(\lambda_{2}) + \dots$$
$$+I_{n}T_{i}(\lambda_{n}) + I_{b}\sum_{k}T_{i}(\lambda_{k})\Delta\lambda_{k}) + N_{d}, \qquad (7)$$

where I_b (R/nm) is the intensity of background continuum emission from the sky. Equation (7) can be rewritten as

$$y_i = t(S_i I_r + B_i I_b), \tag{8}$$

where

1

$$y_i = N_i - N_d, (9)$$

$$S_i(T) = a_i \left(\frac{I_1}{I_r} T_i(\lambda_1) + \frac{I_2}{I_r} T_i(\lambda_2) + \dots + \frac{I_n}{I_r} T_i(\lambda_n) \right),$$

$$B_i = a_i \sum_k T_i(\lambda_k) \Delta \lambda_k.$$
(10)
(11)

 $S_i(T)$ (count/R/s) is the synthetic spectra, which can be determined on the basis of the calibrations described in the previous section. $S_i(T)$ depends on the temperature T (K) of the atmosphere because the relative intensities of rotational airglow bands I_1/I_r , I_2/I_r , ..., I_n/I_r are theoretically determined for each temperature from the transition probabilities, as shown in Fig. 1. The reference line of the OH(6,2), OH(7,3), and $O_2(0,1)$ bands are taken at wavelengths of 846.5555, 877.8271, and 866.0595 nm, respectively. In the present study, the OH(6,2)-band line intensities were calculated using the molecular constants given by Coxon and Foster (1982) with the Einstein transition probability given by Langhoff et al. (1986). For the calculation of the $O_2(0,1)$ band spectrum, we followed the calculation form given by Meinel (1950) with the molecular constants given by Krupenie (1972). The synthetic spectra for the background continuum emission B_i (count nm/R/s) can be also determined from the calibrations.

For each atmospheric temperature, we fit the linear relation of Eq. (8) to the observed airglow spectra for the parameters of I_r and I_b . The fitting is done by a least-square method to minimize the square of the residuals χ^2 , which is given as

$$\chi^{2} = \sum_{i} \frac{1}{\sigma_{i}^{2}} (y_{i} - tS_{i}I_{r} - tB_{i}I_{b})^{2}, \qquad (12)$$

where σ_i^2 is the square of the random error of the output count N_i and N_d and is basically given by the addition of these counts, assuming that they follow the Poisson distribution. The read-out noise of the CCD is usually larger than the random noise from the dark count and should be also taken into account as an error of N_i . For the error of N_i , we need to consider the total count obtained by the integration to the azimuthal direction. Namely, σ_i^2 from N_i is given by $\sigma_i^2 = N_i/m_i$, where m_i is the number of pixels averaged in the azimuthal direction. By this fitting, we obtain the I_r and I_b that make χ^2 minimum for each temperature. This procedure is repeated for all the temperatures from 100 K to 300 K every 1 K, and finally we obtain the three parameters T (K), I_r (R), and I_b (R/nm) that minimize the residual χ^2 . For airglow line emissions without temperature variations (channels 5-10), we simply fit Eq. (8) to the observed spectra to obtain I_r and I_b .

Figure 6 indicates synthetic spectra S_i (thick solid curves counts/R/s) for airglow emissions and synthetic spectra B_i (thick dashed curves in count nm/R/s) for background continuum emissions for Photometer 2. The thin solid curves for banded emissions in Figs. 6(a)-6(d) and 6(h) indicate the contribution from individual emission lines. The synthetic spectra S_i are the summation of the contributions from these lines. For OH and O_2 band emissions, the neighboring lines contaminate each other. Thus, it is not appropriate to take just a peak intensity of each fringe to estimate the line intensity, which is the reason why we use the fitting of the synthetic spectra to the observed fringes to estimate the line intensities correctly. The sodium D-line emission in Fig. 6(h) has two lines at 588.9951 and 589.5924 nm, respectively.

5. Data Processing

Using the three photometers, we made a test measurement of the airglow at Platteville, Colorado (40.2° N, 255.3°E) from September 23 to November 7, 2003. Figure 7 shows examples of the airglow fringe images obtained by Photometer 2 at Platteville on September 25, 2003. A fringe image of OH(7,3) *R*-branches obtained by Photometer 1 is also shown. As described in the previous sections, concentric fringes are obtained for each filter, corresponding to individual airglow lines. From these fringe images, we took the following four data processing steps to calculate rotational temperatures and airglow emission rates.

(1) Cosmic ray removal: The CCD-detector has white spots in the image due to the incidence of cosmic rays. We identify the white spots by checking pixels in which count differences with neighboring pixels exceed a certain threshold and then replace the count of the cosmic-ray pixels by that of the neighboring pixels.

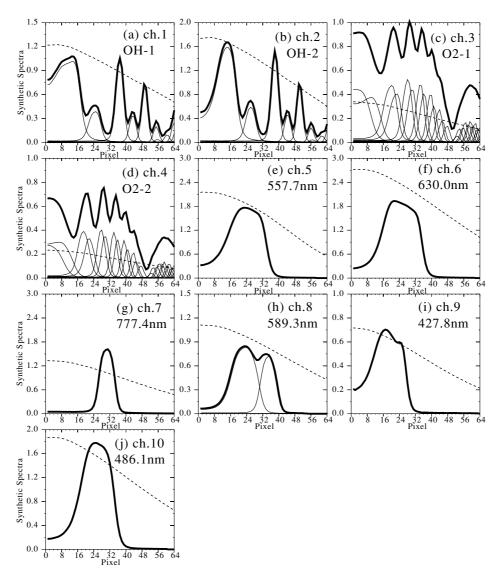


Fig. 6. Synthetic spectra S_i (thick solid curves, in unit of count/R/s) for airglow emissions and synthetic spectra B_i (dashed curves, in unit of count nm/R/s) for background continuum emissions for Photometer 2. The synthetic spectra for OH and O₂ bands are obtained for a temperature of 200 K. The thin solid curves indicate contribution from each airglow line in the banded emission.

(2) Dark count subtraction: The dark images of the CCD, which are necessary to determine the dark counts N_d , are taken every 32.5 min by closing the shutter with the same exposure times as those of the airglow images.

(3) Fringe center determination: To make azimuthal integrations of the concentric fringes, we need to determine the center of the fringes. We first take 12 representative images, sampled by an equal interval from one night of observations. We then make an average image of these 12 images. The fringe center is determined for this average image as the location where the peak height of the azimuthallyintegrated fringes becomes maximum. In other words, if the tentative center is not at the same position as the fringe center, the azimuthal integration would cause reduction of the peak height. We make this fringe-center search for every 0.2 pixels and obtain (x, y) coordinates where the azimuthally-integrated fringe peak becomes maximum. A similar method has been adopted by SATI. We also tried to determine the fringe center by fitting a Gaussian function to the horizontal and vertical cross sections of the fringe images. However, the former method gives a more stable and reliable center location.

(4) Filter temperature drift: In the initial analysis of the photometer data, we found that the peak locations of the fringes are slightly different between the synthetic spectra and the observed spectra. This is because the transmission function $T_i(\lambda_k)$ drifts with changing temperature of the filter. The drift of the center wavelength of a bandpass filter is typically ~0.02 nm/°C due to variations in the filter temperature. The photometer has a sheet heater just below the filter wheel that attempts to keep the filter temperature at 35°C. However, since we cannot put the heater directly on the filter, the filter temperature varies slightly according to changes in the outside temperature. Because we fully calibrate the wavelength dependences of the transmission function as described in Section 3, we can calculate synthetic spectra for the cases when the center wavelength of the filter is shifted by the filter temperature variation. Using a linear interpolation, we calculate synthetic spectra for wavelength shifts of every 0.01 nm for a range of ± 0.4 nm from the cal-

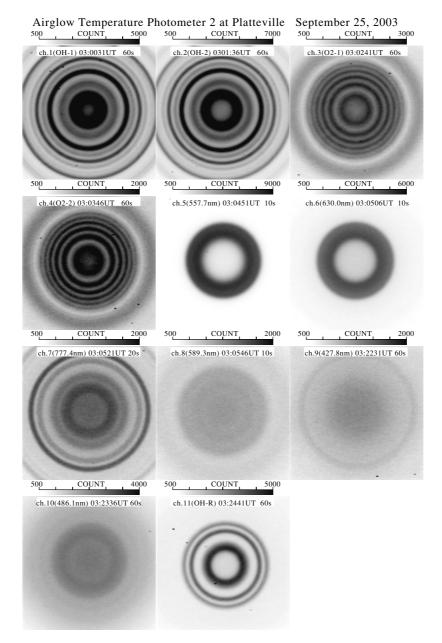


Fig. 7. Examples of the interference fringes for ten filters (ch.1–10) of Photometer 2 and 1 filter (ch.11, OH-R) of Photometer 1. These fringes were obtained at Platteville, Colorado, on September 25, 2003. The channel number, start time of the exposure, and exposure time are indicated at the top of each panel.

ibration data. We fit these synthetic spectra to the observed spectra using Eq. (8) and obtain a best-fit wavelength shift. For OH and O_2 spectra, we assume a rotational temperature of 200 K to obtain the best-fit synthetic spectra.

After these four data processing steps, we fit the synthetic spectra to the observed spectra using Eq. (8) to obtain the rotational temperatures and airglow emission rates. Figure 8 shows examples of the fitting of the synthetic spectra to the observed fringes shown in Fig. 7. The images in Fig. 7 are averaged over the azimuthal direction. The thick and thin curves are the observed and the fitted spectra, respectively. Crosses and vertical dashed lines indicate the data points and the range, respectively, which are used for the spectral fitting.

For OH(6,2) emissions in channels 1 and 2, we fit the synthetic spectra for the two ranges, including the $P_1(2)$

(near pixel 50) and $P_1(4)$ (near pixel 16) peaks, and do not use the peak at $P_1(3)$ (near pixel 38). This is because the $P_1(3)$ line is contaminated by other airglow emissions (e.g., Greet et al., 1998). For $O_2(0,1)$ emissions in channels 3 and 4, we take the fitting range where the emission lines are bunched together between the lines of 865.91 and 867.07 nm. The two major oxygen emissions in channels 5 (557.7 nm) and 6 (630.0 nm) are clearly fitted, while the third oxygen emission in channel 7 at 777.4 nm is very weak and significantly contaminated by the three airglow lines in the OH (9,4) *Q*-branches (Q1(1), Q(2) and Q(3)). The sodium D emissions in channel 8 are also very weak on this night. Since Platteville is at midlatitude, we cannot expect the $N_2^+(1NG)$ auroral emission at 427.8 nm in channel 9, while a weak emission is identified in the Hydrogen Balmer β in channel 10. For OH(7,3) *R*-branches in chan-

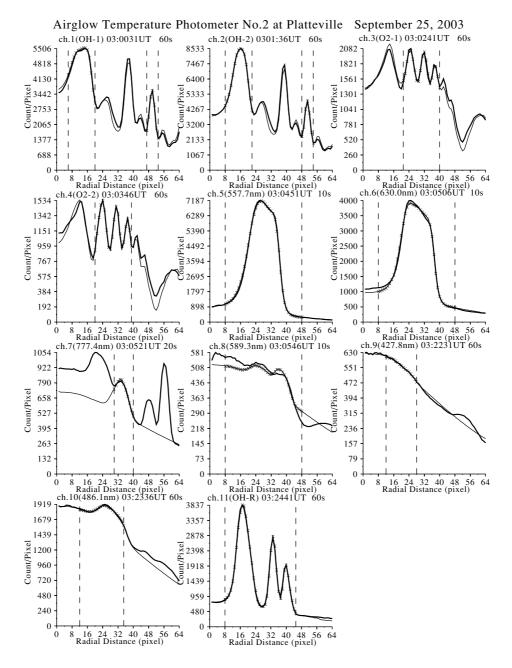


Fig. 8. Cross sections of the interference fringes shown in Fig. 7 (thick curves) and fitted synthetic spectra (thin curves). The images in Fig. 7 are averaged over the azimuthal direction, similarly to that of Figs. 3–6. Crosses and vertical dashed lines in each panel indicate the data points used for the spectral fitting.

nel 11 of Photometer 1, we fit the synthetic spectra to the whole range of the three lines.

Figures 9 and 10 indicate the nocturnal variations of airglow emission rates I_r (R) and rotational temperatures T(K) of OH (solid curves) and O₂ (dashed curves) emissions obtained by the three photometers at Platteville on September 25 and 29, 2003, respectively. The background continuum intensity I_b (R/nm), fitting error (% of maximum count) averaged for all the fitted pixels, and wavelength shift due to the variation of the filter temperature are also shown. Since the three photometers have two filters each for OH and O₂ emissions, six solid and dashed curves are overplotted in this figure. The parameters obtained by the OH(7,3) *R*-branch filter of Photometer 1 are indicated by small crosses. The six filters of OH and O₂ emissions give similar airglow emission rates in Figs. 9(e) and 10(e) with a difference of less than ~20 R. The differences in temperature are mostly less than 10 K, while channels 1 (OH) and 3 (O₂) of Photometer 1 give systematically higher temperatures for both nights, with a difference of ~15–20 K, compared with the temperatures from other filters. The O₂ temperature significantly increases at dawn because of the contamination of twilight. We continue the observation in the twilight until the zenith angle of the Sun becomes larger than -12° .

The fitting errors in Figs. 9(b) and 10(b) are the average difference between the observed and synthetic spectra (in percentage) compared with the peak counts of the fringes and are mostly less than 1%, indicating that the fitting of the synthetic spectra goes well. The wavelength shift due to

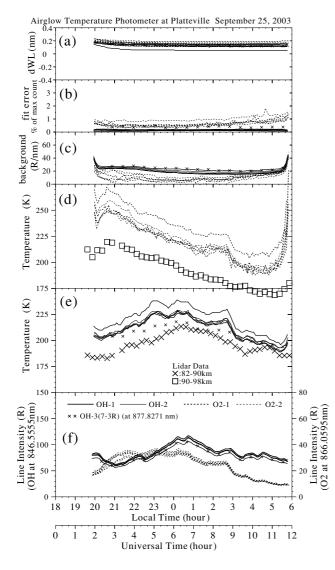


Fig. 9. From top to bottom: (a) wavelength shifts for fitting, (b) average fitting errors (in %) from the maximum count, (c) background intensities, (d) and (e) rotational temperatures, and (f) line intensities, measured by the three airglow temperature photometers at Platteville, Colorado, on September 25, 2003. Six curves are overplotted for OH and O₂, since the three photometers have two each filters for both the OH and O₂ measurements. The parameters obtained by the OH(7,3) *R*-branch filter of Photometer 1 are indicated by small crosses. The crosses and squares indicate temperatures obtained by a sodium lidar at Fort Collins, Colorado and are averaged over 82–90 km and 90–98 km, respectively.

the filter temperature variation in Figs. 9(a) and 10(a) ranges between 0.0 and 0.2 nm, suggesting that the temperatures of the filter during the observation are $\sim 0-10^{\circ}$ C higher than those at the calibration. The large crosses and squares in Figs. 9(d), 9(e), 10(d), and 10(e) indicate the temperatures obtained by a sodium lidar, which we discuss in the next section.

Figures 11 and 12 show airglow emission rates at wavelengths of 557.7, 630.0, 777.4, 589.3, 427.8, and 486.1 nm (channels 5–10), as well as the background continuum intensities and fitting errors obtained by the three photometers at Platteville on September 25 and 29, 2003, respectively. Three curves are overplotted for each airglow line. The three photometers give fairly consistent intensities for these emissions for both nights. The sodium emission inten-

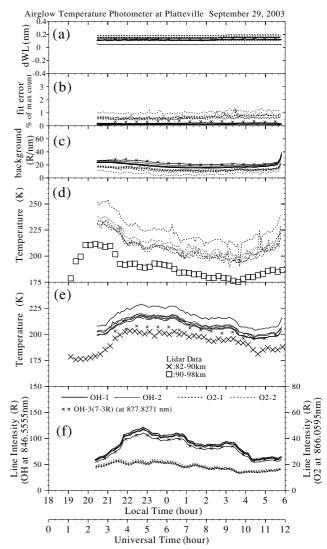


Fig. 10. From top to bottom: (a) wavelength shifts, (b) average fitting errors, (c) background intensities, (d) and (e) rotational temperatures, and (f) line intensities, measured by the three airglow temperature photometers at Platteville, Colorado, on September 29, 2003, in the same format as that in Fig. 9.

sity at 589.3 nm shows a slight difference of \sim 5 R between the photometers. The fitting errors in the top panels are also highest for the sodium emission in two photometers. For auroral lines at 427.8 and 486.1 nm, the noise level of the photometers is very low, indicating that the photometers can measure weak emissions associated with energetic particle precipitation from ring current during magnetic storms at midlatitudes (e.g., Tinsley *et al.*, 1984). The 486.1-nm emission in the evening of both nights may correspond to the geocorona.

6. Comparison with a Sodium Lidar

Sodium lidar can measure the absolute value of the temperature in the middle atmosphere. It gives accurate absolute temperatures with a typical measurement precision of ~ 0.6 K and ~ 5 K near the peak (92 km) and edges (81 and 107 km) of the sodium layer (She *et al.*, 2000). The location of our test measurement, Platteville, was selected to make a comparison with the sodium lidar operated by the Colorado

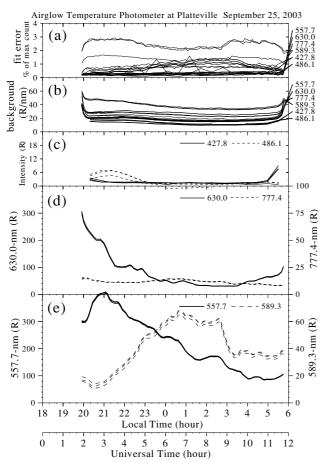


Fig. 11. From top to bottom: (a) average fitting errors (in %) from the maximum count, (b) background intensities, (c) intensities at wavelengths of 427.8 and 486.1 nm, (d) intensities at wavelengths of 630.0 and 777.4 nm, and (e) intensities at 557.7 and 589.3 nm, measured by the three airglow temperature photometers at Platteville, Colorado, on September 25, 2003. Three curves are overplotted for all the parameters.

State University (CSU) at Fort Collins (40.6° N, 254.9°E), Colorado. The sodium lidar is located ~60 km northwest of Platteville. The lidar has a northward and an eastward beam, which crosses the mesopause region about 100 km NNW and 50 km NNE from Platteville, respectively. The field-of-view (16°) of the photometers corresponds to a circular area with a diameter of ~50 km at the altitudes of the OH and O₂ airglow layers. The relative locations of Platteville, CSU, and the lidar beams were shown by She *et al.* (2004). Several researchers have used the mesospheric temperature data from the CSU lidar for comparison with the temperatures from airglow photometers and spectrometers (e.g., She and Lowe, 1998; Melo *et al.*, 2001; Taylor *et al.*, 2001).

The large crosses and squares in Figs. 9(d), 9(e), 10(d), and 10(e) indicate temperatures obtained by the CSU sodium lidar with a time resolution of 15 min. The temperatures are averaged for the two beams and altitude ranges of 82–90 km and 90–98 km, which correspond to the typical airglow layers of OH and O₂ emissions, respectively. The variations of the rotational temperatures obtained by the photometers are similar to the variations of the lidar temperatures. However, the absolute values of the photometer temperatures are systematically higher than the lidar tem-

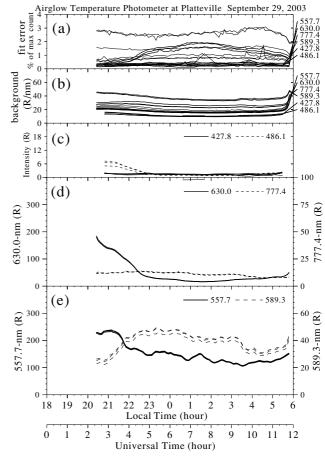


Fig. 12. From top to bottom: (a) average fitting errors (in %) from the maximum count, (b) background intensities, (c) intensities at wavelengths of 427.8 and 486.1 nm, (d) intensities at wavelengths of 630.0 and 777.4 nm, and (e) intensities at 557.7 and 589.3 nm, measured by the three airglow temperature photometers at Platteville, Colorado, on September 29, 2003, in the same format as that in Fig. 11.

peratures with differences of 20–30 K for both OH and O_2 emissions for both nights.

To investigate the temperature difference between the photometers and the lidar more systematically, we made a statistical comparison of the temperatures using eight nights (September 23 and 25–29 and October 1 and 5, 2003) of simultaneous observations by the photometers and the lidar. The results are shown in Fig. 13, which is the correlation of the temperatures obtained by the photometers and by the sodium lidar. The lidar temperatures are averaged over altitudes of 82–90 km for comparison with the OH temperatures and 90–98 km for comparison with the O₂ temperatures. The solid lines indicate the linear regression lines of

$$T_{\text{lidar}}(\mathbf{K}) = aT_{\text{photometer}}(\mathbf{K}) + b.$$
(13)

For all 13 filters of the three photometers plotted in Fig. 13, the photometer temperatures are linearly correlated with the lidar temperature. The correlation coefficient r is mostly larger than 0.8 except for channels 1 and 11 of Photometer 1 ($r \sim 0.7$). The correlations for the O₂ temperatures are generally better than those for the OH temperatures. The photometer temperatures are systematically lower than the lidar temperatures for all the channels.

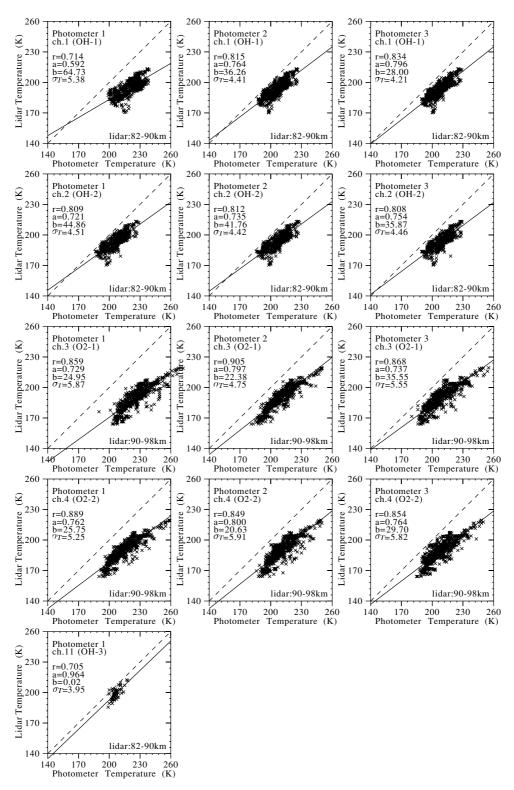


Fig. 13. Correlations of temperatures obtained by the three airglow temperature photometers at Platteville and by a sodium lidar at Fort Collins. The lidar temperatures are averaged over altitudes of 82–90 km for comparison with the OH temperatures and 90–98 km for comparison with the O_2 temperatures. The solid lines are the linear fitting lines. *r*, *a*, *b*, and σ_T are correlation coefficient, gradient and zero-crossing of the linear fitting lines, and standard deviation from the linear fitting lines, respectively.

The correlation coefficient r, gradient a, and zerocrossing b (K) of the linear fitting lines, and the standard deviation σ_T (K) from the linear fitting lines are listed in Table 2. The lidar temperatures are averaged over ± 4 km and ± 2 km from the typical altitudes of emission peak at 86 km for the OH emissions and 94 km for the O₂ emissions. The correlation coefficient *r* is clearly larger for the lidar temperatures averaged over ± 4 km for all channels. The correlation coefficient *r* for temperatures from the OH(7,3) *R*-branch (channel 11 of Photometer 1) is lower than those for temperatures from the OH(6,2) *P*-branch (channels 1 and 2). As shown in the values of σ_T , we can convert the ro-

Table 2. Correlations and linear fitting parameters of temperatures between the sodium lidar and the airglow temperature photometers. Better correlation is obtained for the lidar temperatures averaged over 82–90 km and 90–98 km.

Photometer	Channel	Correlation	а	b	σ_T					
				(K)	(K)					
Lidar altitude: OH:82–90 km, O2:90–98 km										
1	1 (OH-1)	0.714	0.592	64.7	5.4					
1	2 (OH-2)	0.809	0.721	44.9	4.5					
1	3 (O ₂ -1)	0.859	0.729	24.9	5.9					
1	4 (O ₂ -2)	0.889	0.762	25.7	5.2					
1	11 (OH-3)	0.705	0.964	0.0	3.9					
2	1 (OH-1)	0.815	0.764	36.3	4.4					
2	2 (OH-2)	0.812	0.735	41.8	4.4					
2	3 (O ₂ -1)	0.905	0.797	22.4	4.8					
2	4 (O ₂ -2)	0.849	0.800	20.6	5.9					
3	1 (OH-1)	0.834	0.796	28.0	4.2					
3	2 (OH-2)	0.808	0.754	35.9	4.5					
3	3 (O ₂ -1)	0.868	0.737	35.5	5.6					
3	4 (O ₂ -2)	0.854	0.764	29.7	5.8					
Lidar altitude: OH:84-88 km, O2:92-96 km										
1	1 (OH-1)	0.636	0.630	56.1	7.1					
1	2 (OH-2)	0.742	0.789	30.2	6.1					
1	3 (O ₂ -1)	0.826	0.756	18.6	7.0					
1	4 (O ₂ -2)	0.860	0.795	18.5	6.3					
1	11 (OH-3)	0.685	1.271	-63.5	5.5					
2	1 (OH-1)	0.749	0.833	21.8	6.0					
2	2 (OH-2)	0.749	0.805	27.1	6.0					
2	3 (O ₂ -1)	0.872	0.829	15.6	5.9					
2	4 (O ₂ -2)	0.819	0.832	13.6	6.9					
3	1 (OH-1)	0.776	0.880	10.2	5.7					
3	2 (OH-2)	0.748	0.830	19.9	6.0					
3	3 (O ₂ -1)	0.845	0.774	27.6	6.5					
3	4 (O ₂ -2)	0.824	0.795	23.1	6.8					

tational temperatures obtained by the photometers to the lidar temperatures using these parameters with Eq. (13) with standard deviations of 4–6 K.

In the above comparison with the lidar data, we simply averaged the lidar temperatures for the given altitude ranges. To obtain the altitude averages, we also tried to use a Gaussian weighting function for the given altitude ranges with standard deviations of the half width of the altitude ranges. The results were almost the same as those from the simple averages. The differences in temperatures in Figs. 9 and 10 were mostly less than 5 K. The differences in correlation coefficients in Table 2 were less than 0.03.

Figure 14 shows a comparison of the temperatures obtained by the photometers and the lidar. The photometer temperatures are corrected using Eq. (13) with the parameters listed in the upper part of Table 2 (average for ± 4 km). All the temperatures in six curves and small crosses from the three photometers fit well with the lidar temperatures, which are indicated by large crosses and squares. The temperatures are temporally different at 02-03 LT in Fig. 14(c) and at 20-21 LT, 01-02 LT, and 04-05 LT in Fig. 14(d). These differences may be because of the height variation of the airglow emissions associated with gravity waves. The

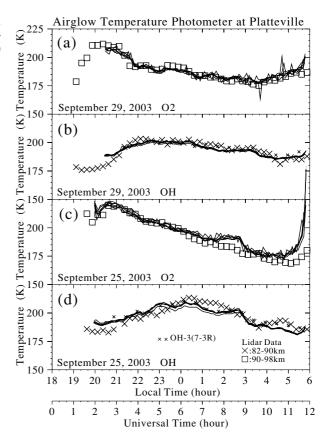


Fig. 14. Comparison of the temperatures obtained by the sodium lidar (squares and large crosses) and by the three airglow temperature photometers (solid curves and small crosses) for the nights of September 25 and 29, 2003. The temperatures of the photometers are corrected by the linear fitting parameters listed in Fig. 13 and Table 2. Six solid curves are overplotted in each panel.

significant increase in photometer temperatures at 05-06 LT in Fig. 14(c) is because of contamination by twilight. We did not include the time interval of the twilight observations in the correlation analyses in Fig. 13 and Table 2.

7. Discussion

The absolute temperatures obtained by the three photometers are systematically higher than the temperatures obtained by the near-collocated sodium lidar, as shown in Figs. 9, 10, and 13. Here we discuss the possible causes of this temperature difference.

The temperature of the interference filter drifts according to the variations in the outside temperature. As a result, the interference fringes shift in radial direction. As discussed in data processing step (4) of Section 5, we correct this fringe drift by calculating the best-fit synthetic spectra. This correction may cause a systematic offset of the absolute temperature.

The drift of the fringe corresponds to a shift of less than 0.2 nm in wavelength range, as shown in Figs. 9(a) and 10(a). This wavelength shift of the filter causes a fringe shift of less than 1 pixel in radial distances. On the other hand, the transmission of the optics decreases with increasing radial distance, as shown in Figs. 3 and 4. This decrease is roughly about 1% per pixel. Thus, if we calibrate the wavelength shift of the filter incorrectly, it may cause a maxi-

mum of a 1% difference in the estimation of peak intensity of airglow emission. For OH(6,2) rotational temperatures at T = 200 K, the 1% difference of the peak intensity ratio of P₁(4)/P₁(2) corresponds to the rotational temperature difference of only ~2 K. From these estimations, we conclude that the filter wavelength drift does not significantly affect the estimation of the absolute temperature. The average fitting errors shown in Figs. 9(b) and 10(b) are also less than 1%, corresponding to a random error of rotational temperatures of less than ~2 K.

After the calibration of the photometers we noticed a possibility that the wavelength of the monochromatic calibration source, which is a grating spectrometer, might shift during the calibration due to a temperature change of the grating plate. Using another grating spectrometer, we found that the wavelength of the spectrometer shifted ~ 0.3 nm during a few hours due to heat flux from the halogen lamp that was used as the light source. This shift can be monitored by using emission lines from a mercury lamp. However, we did not know how much the wavelength of the spectrometer was shifted during the calibration of the photometers, since we did not conduct frequent calibration of spectrometer wavelengths during the calibration of the photometers. Thus, we made a model calculation for those cases where the wavelength of the spectrometer shifts ± 0.5 nm from the used values. The differences of the output temperatures between the non-shifted and shifted calibration data for the data of September 25, 2003 were less than 2 K for both OH and O_2 temperatures, except for the cases that the fitting failed because of too much shift. Thus, we conclude that the wavelength shift of the grating spectrometer used for the calibration does not cause a significant error to the output temperatures.

Osterbrock *et al.* (2000) have shown high-resolution airglow spectra obtained by the Keck astronomical facility at Mauna Kea, Hawaii. The wavelengths of OH and O_2 emission lines in their high-resolution spectra are slightly different from the theoretical spectra used in the present study (Fig. 1) and are in order of 0.01 nm. Thus, considering the above analysis of the possible wavelength shift of the filter and the grating spectrometer, this inaccuracy of the wavelengths of airglow lines would also not cause significant errors in the output temperatures.

The transition probabilities which are used to calculate the rotational temperatures from the observed intensity ratio of rotational lines contain some ambiguity. Greet *et al.* (1998) showed in their Table 2 that the temperature corrections using the transition probabilities of Langhoff *et al.* (1986) (used in this paper) is -14 K for the OH(6,2) P₁(2)/P₁(4) ratio. French *et al.* (2000) estimated the differences in OH rotational temperatures to be ~11 K for three transition probabilities by Mies (1974), Langhoff *et al.* (1986), and Turnbull and Lowe (1989), respectively.

The other possible reason for the high rotational temperatures compared with the lidar temperatures is the assumption of thermodynamic equilibrium for the rotational levels. Pendleton *et al.* (1993) have shown that for high rotational quantum numbers, the OH rotational populations can strongly deviate from the thermodynamic equilibrium values. If the rotational levels are not in thermodynamic equilibrium, the estimated temperature would become higher than the atmospheric temperature.

Despite the large difference in absolute temperatures, the linear regression parameters listed in Table 2 (averaged over 82-90 km and 90-98 km) correct the photometer temperatures to the lidar temperature very well, with differences of 4-6 K in standard deviation. This difference is possibly because of the height variation of the airglow layers. The peak height of the airglow layers can vary a few kilometers over time because of gravity waves and tides (e.g., Zhang et al., 1993; Zhang and Shepherd, 1999; Fujii et al., 2004). It should be noted that Zhao et al. (2005) have made a similar comparison of lidar and photometer temperatures using data collected during 16 nights at Hawaii (20.8°N, 156.2°W). They found that the tides or long-period gravity waves can cause a systematic decrease in the altitudes of both OH and O₂ emission layers by up to several kilometers. This effect caused differences of temperature up to ~ 10 K in their comparison. The linear regression lines obtained by the present analysis should contain ambiguities due to this effect of tidal forcing to the airglow layer height.

8. Concluding Remarks

In this paper, we report in detail the optical configuration, calibration, and data processing of the three airglow temperature photometers as well as a comparison with the CSU lidar. Although the rotational temperature measurement contains several assumptions of airglow layer height, transition probabilities, and thermodynamic equilibrium, it is still useful to monitor the mesospheric temperature because the photometer is a compact instrument and easily automated. This advantage of the photometer makes it suitable for network measurement of the mesospheric temperatures at multiple stations. The good temperature correlation among the 13 filters of the three photometers and between the photometers and the lidar guarantees such a network measurement. The three photometers are currently in operation at Rikubetsu (43.5°N, 143.8°E), Sata (31.0°N, 130.7°E), Japan, and Kototabang, Indonesia (0.2°S, 100.3°E) to monitor latitudinal difference of global-scale waves in the mesosphere. The present result also indicates that the cross calibration is essentially important for the network measurement of rotational temperatures.

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